

Production inventory system for deteriorating items with trapezoidal type demand *

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Abstract For the items like trendy goods, mobile phones and such others, it is examined that the demand rate is of trapezoidal type. The aim of this study is to present optimal production policy for deteriorating items, when the demand of an item is trapezoidal type. Rate of deterioration is assumed to be constant and rate of production depends upon demand rate. Shortages are not allowed. Mathematical formulation is derived in order to minimize the total cost of an inventory system. An easy to use algorithm is presented to decide an optimal production policy.

Key words Inventory system, EPQ model, Trapezoidal type demand, Deterioration, Minimizing Total Cost.

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1 Introduction

In recent competitive market, it is observed that for items like fancy/seasonal/trendy goods, the demand of an item increases with respect to time over a period of time. Thereafter, the item consumed by level demand for a short period, followed by a decrease in demand with time again. Resh et al. [19] and Donaldson [9] made first attempts to integrate the linear trend in demand for an inventory system. For the first time, Hill [15] considered ramp type demand pattern to develop an optimal ordering policy. In case of ramp type demand rate, the rate increases linearly with time and thereafter it stabilizes. Such demand pattern is observed in newly introduced consumable items in the market. Many researchers have studied models with ramp type demand. The inventory models with the ramp type demand are studied by Wu et al. [28, 29], Wu and Ouyang [27], Wu [26], Giri et al. [11], Deng [7], Chen et al. [2], Deng et al. [8], Cheng and Wang [3], He et al. [14], Skouri et al. [23]. Moreover, the goods in the inventory system always retain their physical quality is not true in common. In current business environment, effect of deterioration is expected to be incorporated in an inventory system. The process

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which depletes the present value or usefulness of an item and does not allow their original use, due to degradation, spoilage, evaporation etc. is known as deterioration. First of all Ghare and Schrader [10] incorporated deterioration in an inventory system. Covert and Philip [5] used Weibull distribution to extend the idea of Ghare and Schrader [10]. Dave and Patel [6], Goyal [13], Raafat [18], Shah and Shah [21], Goyal and Giri [12], Manna and Chaudhri [17], Skouri et al. [24], Ruxin et al. [20] and Bakker et al. [1] cite an up to date review on deteriorating inventory system. Cheng and Wang [3] extended this idea from ramp type demand to trapezoidal type demand. Cheng et al [4] integrated shortages with partial backlogging and deterioration in an inventory system to extend the idea of Cheng and Wang [3]. Recent articles on trapezoidal type demand by Shukla and Suthar [22], Wu et. al. [30, 31], Vandana and Shrivastava [25]. Manna et al. [16] present production inventory system for deteriorating items having ramp type demand. The demand rate increases with time up to a certain point of time and then stabilizes at constant level. Models were formulated without shortages and with two assumptions that: a) the demand rate is stabilized after the production stops and before the time when inventory level reaches to zero and b) the deterioration is constant.

Our present work is an extension of the work of Manna et al. [16] with the assumption that the production process stops before the inventory level reaches to zero and in one of the three situations: 1) before the demand rate becomes constant, 2) when the demand rate is constant and 3) after the demand rate is constant. In this paper, section 1 introduces the article in brief. Assumptions and notations are presented in section 2. Section 3 deals with the mathematical formulation for each of the three cases along with the computational algorithm and the conclusions are described in section 4.

2 Assumptions and notations

To formulate the proposed inventory system mathematically, the following assumptions are made and the notations to be used by us in this paper are also explained below:

1. The inventory system deals with a single item. Rate of replenishment rate is assumed to be finite and lead time is considered to be zero or negligible. The length of planning horizon is infinite. Inventory system does not possess shortages.
2. The function $Q(t)$ represents level of an stock at any instant of time t during $[0, T]$, where T is length of ordering cycle.
3. The demand is assumed to be trapezoidal type, say $R(t)$, where $R(t) = \begin{cases} a_1 + b_1 t & ; \quad 0 \leq t \leq \lambda_1 \\ a_1 + b_1 \lambda_1 & ; \quad \lambda_1 \leq t \leq \lambda_2 \\ a_2 - b_2 t & ; \quad \lambda_2 \leq t \leq T \end{cases}$, where a_1, a_2, b_1, b_2 are scaling parameters for rate of demand. During $[0, \lambda_1]$ demand increases with respect to time, then it stabilizes during $[\lambda_1, \lambda_2]$ and thereafter it decreases as t increases during $[\lambda_2, T]$.
4. The level of stock deteriorates with a constant rate say θ ($0 < \theta < 1$) during the ordering cycle $[0, T]$. Again, deteriorated stock is neither repaired nor replaced during $[0, T]$.
5. Inventory system is assumed as production inventory system, where initial stock level is assumed to be zero at time $t = 0$. Production process starts at $t = 0$ and continues up to time $t = t_1$. At time $t = t_1$, stock level attains its maximum say S .
6. The unit production cost of an item is defined as $C_p = \alpha_1 (R(t))^{-\gamma}$, where $\gamma > 0$ and $\gamma \neq 2$ (Manna et. al [16]). $\alpha_1 > 0$ as $C_p > 0$ and $R(t)$ is non – negative. As demand increases unit production cost will decrease, which validates that C_p and $R(t)$ are in inverse proportion.
7. We consider C_h is the holding cost / unit; C_d is the cost due to deterioration / unit; $C(t_1, T)$ is an average cost of an inventory system.

3 Mathematical formulation and computational algorithm

As, $Q(t)$ represents level of stock at any instant of time t (say) during $[0, T]$. Initially level of stock is assumed to be zero at $t = 0$, at the same time production takes place and continues up to time $t = t_1$ with maximum stock level say S . Hence, during $[0, t_1]$

$$\frac{dQ}{dt} + \theta Q(t) = \begin{cases} (\beta - 1)R(t) & ; \quad 0 \leq t \leq t_1 \\ -R(t) & ; \quad t_1 \leq t \leq T \end{cases} \quad (3.1)$$

Now depending upon the value of t_1 the following three different cases may arise:

Case 1: $0 \leq \lambda_1 \leq \lambda_2 \leq t_1 \leq T$, Case 2: $0 \leq \lambda_1 \leq t_1 \leq \lambda_2 \leq T$ and Case 3: $0 \leq t_1 \leq \lambda_1 \leq \lambda_2 \leq T$. Hence, we compute below separately for all the cases for the proposed production inventory system.

Case 1: $0 \leq \lambda_1 \leq \lambda_2 \leq t_1 \leq T$

At time $t = 0$, the production starts with zero stock level and stops at time $t = t_1$. Using (3.1)

$$\frac{dQ}{dt} + \theta Q(t) = \begin{cases} (\beta - 1)(a_1 + b_1 t) & ; \quad 0 \leq t \leq \lambda_1 \\ (\beta - 1)(a_1 + b_1 \lambda_1) & ; \quad \lambda_1 \leq t \leq \lambda_2 \\ (\beta - 1)(a_2 - b_2 t) & ; \quad \lambda_2 \leq t \leq t_1 \\ -(a_2 - b_2 t) & ; \quad t_1 \leq t \leq T \end{cases} \quad (3.2)$$

Using initial condition $Q(0) = 0$, we solve

$$\frac{dQ}{dt} + \theta Q(t) = (\beta - 1)(a_1 + b_1 t); \quad 0 \leq t \leq \lambda_1 \quad (3.3)$$

Its solution is

$$Q(t) = \frac{(\beta - 1)(e^{\theta t} b_1 t \theta + e^{\theta t} a_1 \theta - e^{\theta t} b_1 - a_1 \theta + b_1) e^{-\theta t}}{\theta^2} \quad (3.4)$$

Using continuity of $Q(t)$ at $t = \lambda_1$ we solve

$$\frac{dQ}{dt} + \theta Q(t) = (\beta - 1)(a_1 + b_1 \lambda_1); \quad \lambda_1 \leq t \leq \lambda_2 \quad (3.5)$$

which results in

$$Q(t) = -\frac{\left(\begin{array}{l} e^{-\theta t} b_1 \beta \lambda_1 \theta - e^{\theta t} a_1 \beta \theta + e^{\theta t} b_1 \lambda_1 \theta + e^{\theta \lambda_1} b_1 \beta + e^{\theta t} a_1 \theta \\ + a_1 \beta \theta - e^{\theta \lambda_1} b_1 - a_1 \theta - b_1 \beta + b_1 \end{array} \right) e^{-\theta t}}{\theta^2} \quad (3.6)$$

Similarly, using continuity of $Q(t)$ at $t = \lambda_2$ we solve,

$$\frac{dQ}{dt} + \theta Q(t) = (\beta - 1)(a_2 - b_2 t); \quad \lambda_2 \leq t \leq t_1 \quad (3.7)$$

which gives

$$Q(t) = \frac{1}{\theta^2} \left(e^{-\theta t} \left(\begin{array}{l} e^{\theta \lambda_2} b_1 \beta \lambda_1 \theta + e^{\theta \lambda_2} b_2 \beta \lambda_2 \theta - e^{\theta t} b_2 \beta t \theta + e^{\theta \lambda_2} a_1 \beta \theta - e^{\theta \lambda_2} a_2 \beta \theta \\ - e^{\theta \lambda_2} b_1 \lambda_1 \theta - e^{\theta \lambda_2} b_2 \lambda_2 \theta + e^{\theta t} a_2 \beta \theta + e^{\theta t} b_2 t \theta - e^{\theta \lambda_2} a_1 \theta + e^{\theta \lambda_2} a_2 \theta \\ - e^{\theta \lambda_2} b_2 \beta - e^{\theta t} a_2 \theta + e^{\theta t} b_2 \beta - e^{\theta \lambda_1} b_1 \beta - a_1 \beta \theta + e^{\theta \lambda_2} b_2 - e^{\theta t} b_2 \\ + e^{\theta \lambda_1} b_1 + a_1 \theta + b_1 \beta - b_1 \end{array} \right) \right) \quad (3.8)$$

Moreover, at time $t = t_1$, level of stock is maximum, using $Q(t_1) = S$ we solve,

$$\frac{dQ}{dt} + \theta Q(t) = -(a_2 - b_2 t); \quad t_1 \leq t \leq T \quad (3.9)$$

which yields

$$Q(t) = \frac{1}{\theta^2} \left(\begin{array}{l} e^{-\theta(t-t_1)} S \theta^2 - e^{-\theta(t-t_1)} b_2 t_1 \theta + e^{-\theta(t-t_1)} a_2 \theta \\ + b_2 t \theta + e^{-\theta(t-t_1)} b_2 - a_2 \theta - b_2 \end{array} \right) \quad (3.10)$$

Using the boundary condition $Q(T) = 0$ in (3.10), we evaluate the maximum level of stock as under:

$$S = -\frac{1}{\theta^2} \left(b_2 t_1 \theta + a_2 \theta + b_2 T \theta e^{\theta(T-t_1)} + b_2 - (a_2 \theta + b_2) e^{\theta(T-t_1)} \right) \quad (3.11)$$

By substituting S in (3.10), we have $Q(t)$ as under, during $[t_1, T]$

$$Q(t) = -\frac{1}{\theta^2} \left(e^{\theta(T-t)} T b_2 \theta - e^{\theta(T-t)} a_2 \theta - b_2 t \theta - e^{\theta(T-t)} b_2 + a_2 \theta + b_2 \right) \quad (3.12)$$

Using (3.4), (3.6), (3.8) and (3.12), the total inventory during $[0, T]$ is ,

$$TI_1 = \int_0^T Q(t) dt = \int_0^{\lambda_1} Q(t) dt + \int_{\lambda_1}^{\lambda_2} Q(t) dt + \int_{\lambda_2}^{t_1} Q(t) dt + \int_{t_1}^T Q(t) dt \quad (3.13)$$

where,

$$\begin{aligned} \int_0^{\lambda_1} Q(t) dt &= \frac{1}{2\theta^3} \left(\begin{pmatrix} b_1\beta\lambda_1^2\theta^2 + 2a_1\beta\lambda_1\theta^2 - b_1\lambda_1^2\theta^2 - 2a_1\theta^2\lambda_1 \\ -2b_1\beta\lambda_1\theta - 2a_1\beta\theta + 2b_1\lambda_1\theta + 2a_1\theta + 2b_1\beta - 2b_1 \\ +e^{-\theta\lambda_1}(2a_1\beta\theta - 2a_1\theta - 2\beta b_1 + 2b_1) \end{pmatrix} \right) \\ \int_{\lambda_1}^{\lambda_2} Q(t) dt &= \\ &- \frac{1}{\theta^3} \left(b_1\beta\lambda_1^2\theta^2 - b_1\beta\lambda_1\lambda_2\theta^2 + a_1\beta\lambda_1\theta^2 - a_1\beta\lambda_2\theta^2 - b_1\lambda_1^2\theta^2 + b_1\lambda_1\lambda_2\theta^2 \right. \\ &\left. - a_1\lambda_1\theta^2 + a_1\lambda_2\theta^2 + b_1\beta + a_1\beta\theta e^{-\theta\lambda_1} - b_1\beta e^{\theta(\lambda_1-\lambda_2)} - e^{-\theta\lambda_2}a_1\beta\theta - b_1 \right) \\ &- \frac{1}{\theta^3} \left(-a_1\theta e^{-\theta\lambda_1} - b_1\beta e^{-\theta\lambda_1} + b_1e^{\theta(\lambda_1-\lambda_2)} + e^{-\theta\lambda_2}a_1\theta + e^{-\theta\lambda_2}b_1\beta + e^{-\theta\lambda_1}b_1 - e^{-\theta\lambda_2}b_1 \right) \\ \int_{\lambda_2}^{t_1} Q(t) dt &= \\ &- \frac{1}{2\theta^3} \left(\begin{aligned} &-2b_2 + 2a_2\beta\lambda_2\theta^2 - 2a_2\beta t_1\theta^2 - 2b_2\beta t_1\theta - b_2\beta\lambda_2^2\theta^2 + b_2\beta t_1^2\theta^2 \\ &-2b_1\beta\lambda_1\theta + 2b_2\beta + 2a_1\theta - 2a_2\theta - 2a_1\beta\theta + 2a_2\beta\theta + 2b_1\lambda_1\theta - 2a_2\lambda_2\theta^2 \\ &+2a_2t_1\theta^2 + 2b_2t_1\theta + b_2\lambda_2^2\theta^2 - b_2t_1^2\theta^2 \end{aligned} \right) \\ &- \frac{1}{2\theta^3} e^{-\theta(\lambda_2+t_1)} \left(\begin{aligned} &2e^{\theta t_1}b_1 - 2e^{\theta(\lambda_1+t_1)}b_1 + 2e^{\theta\lambda_2}a_1\theta - 2e^{\theta t_1}b_1\beta + 2e^{\theta(\lambda_1+\lambda_2)}b_1 - 2e^{\theta\lambda_2}a_1\beta\theta \\ &-2e^{\theta t_1}a_1\theta + 2e^{\theta t_1}a_1\beta\theta - 2e^{2\theta\lambda_2}a_2\beta\theta + 2e^{2\theta\lambda_2}a_1\beta\theta - 2e^{2\theta\lambda_2}b_2\lambda_2\theta \\ &-2e^{2\theta\lambda_2}b_1\lambda_1\theta + 2e^{2\theta\lambda_2}b_2 - 2e^{2\theta\lambda_2}a_1\theta + 2e^{2\theta\lambda_2}a_2\theta - 2e^{2\theta\lambda_2}b_2\beta \\ &-2e^{\theta(\lambda_1+\lambda_2)}b_1\beta + 2e^{2\theta\lambda_2}b_1\beta\lambda_1\theta + 2e^{2\theta\lambda_2}b_2\beta\lambda_2\theta - 2e^{2\theta\lambda_2}b_1 + 2e^{2\theta\lambda_2}b_1\beta \end{aligned} \right) \\ \int_{t_1}^T Q(t) dt &= \frac{1}{2\theta^3} \left(\begin{aligned} &T^2b_2\theta^2 - b_2t_1^2\theta^2 - 2Ta_2\theta^2 + 2a_2\theta^2t_1 + 2b_2t_1\theta - 2e^{\theta(T-t_1)}Tb_2\theta \\ &-2a_2\theta + 2e^{\theta(T-t_1)}a_2\theta - 2b_2 + 2e^{\theta(T-t_1)}b_2 \end{aligned} \right) \end{aligned}$$

Now, total number of deteriorated units during $[0, T]$ is given by,

$DI_1 =$ Production in $[0, \lambda_1]$ + Production in $[\lambda_1, \lambda_2]$ + Production in $[\lambda_2, t_1]$ - Demand in $[0, \lambda_1]$ - Demand in $[\lambda_1, \lambda_2]$ - Demand in $[\lambda_2, T]$

$$\begin{aligned} &= \beta \int_0^{\lambda_1} (a_1 + b_1t) dt + \beta \int_{\lambda_1}^{\lambda_2} (a_1 + b_1\lambda_1) dt + \beta \int_{\lambda_2}^{t_1} (a_2 - b_2t) dt \\ &\quad - \int_0^{\lambda_1} (a_1 + b_1t) dt - \int_{\lambda_1}^{\lambda_2} (a_1 + b_1\lambda_1) dt - \int_{\lambda_2}^T (a_2 - b_2t) dt \\ &= -\frac{1}{2}\beta b_1\lambda_1^2 + \beta b_1\lambda_1\lambda_2 + \beta a_1\lambda_2 + \frac{1}{2}\beta b_2\lambda_2^2 - \frac{1}{2}\beta b_2t_1^2 - \beta a_2\lambda_2 \\ &\quad + \beta a_2t_1 + \frac{1}{2}b_1\lambda_1^2 - b_1\lambda_1\lambda_2 - a_1\lambda_2 + \frac{1}{2}T^2b_2 - \frac{1}{2}b_2\lambda_2^2 - a_2T + a_2\lambda_2 \end{aligned} \quad (3.14)$$

Cost of production during $[0, t_1]$ is given by,

$$\begin{aligned} PC_1 &= \int_0^{t_1} \beta\alpha_1 (R(t))^{(1-\gamma)} du \\ &= \int_0^{\lambda_1} \beta\alpha_1 (a_1 + b_1u)^{(1-\gamma)} du + \int_{\lambda_1}^{\lambda_2} \beta\alpha_1 (a_1 + b_1\lambda_1)^{(1-\gamma)} du + \int_{\lambda_2}^{t_1} \beta\alpha_1 (a_2 - b_2u)^{(1-\gamma)} du \\ &= \beta\alpha_1 \left(\frac{-a_1^\gamma + (b_1\lambda_1 + a_1)^\gamma}{b_1\gamma} + (b_1\lambda_1 + a_1)^{\gamma-1}(\lambda_2 - \lambda_1) + \frac{(-b_2\lambda_2 + a_2)^\gamma - (a_2 - Tb_2)^\gamma}{b_2\gamma} \right) \end{aligned} \quad (3.15)$$

Case 2: $0 \leq \lambda_1 \leq t_1 \leq \lambda_2 \leq T$

In this case, from (3.1),

$$\frac{dQ}{dt} + \theta Q(t) = \begin{cases} (\beta - 1)(a_1 + b_1 t) & ; \quad 0 \leq t \leq \lambda_1 \\ (\beta - 1)(a_1 + b_1 \lambda_1) & ; \quad \lambda_1 \leq t \leq t_1 \\ -(a_1 + b_1 \lambda_1) & ; \quad t_1 \leq t \leq \lambda_2 \\ -(a_2 - b_2 t) & ; \quad \lambda_2 \leq t \leq T \end{cases} \quad (3.16)$$

We solve differential equation given below, using initial condition $Q(0) = 0$,

$$\frac{dQ}{dt} + \theta Q(t) = (\beta - 1)(a_1 + b_1 t); \quad 0 \leq t \leq \lambda_1 \quad (3.17)$$

whose solution is

$$Q(t) = \frac{(\beta - 1)}{\theta^2} (b_1 t \theta + a_1 \theta - b_1 - (a_1 \theta - b_1) e^{-\theta t}) \quad (3.18)$$

We use continuity of $Q(t)$ at $t = \lambda_1$ to solve the differential equation,

$$\frac{dQ}{dt} + \theta Q(t) = (\beta - 1)(a_1 + b_1 \lambda_1); \quad \lambda_1 \leq t \leq t_1 \quad (3.19)$$

which gives

$$Q(t) = -\frac{1}{\theta^2} \begin{pmatrix} b_1 \beta \lambda_1 \theta - a_1 \beta \theta + b_1 \lambda_1 \theta + b_1 \beta e^{\theta(\lambda_1 - t)} + a_1 \theta + a_1 \beta \theta e^{-\theta t} \\ -b_1 e^{\theta(\lambda_1 - t)} - (a_1 \theta + b_1 \beta - b_1) e^{-\theta t} \end{pmatrix} \quad (3.20)$$

Now at $t = t_1$ the production process stops and the maximum level of stock is S , i.e. $Q(t_1) = S$. We solve,

$$\frac{dQ}{dt} + \theta Q(t) = -(a_1 + b_1 \lambda_1); \quad t_1 \leq t \leq \lambda_2 \quad (3.21)$$

for which we have

$$Q(t) = \frac{1}{\theta} \left(e^{-\theta(t-t_1)} S \theta + e^{-\theta(t-t_1)} b_1 \lambda_1 + e^{-\theta(t-t_1)} a_1 - b_1 \lambda_1 - a_1 \right) \quad (3.22)$$

Using continuity of $Q(t)$ at $t = \lambda_2$, we solve the differential equation,

$$\frac{dQ}{dt} + \theta Q(t) = -(a_2 - b_2 t); \quad \lambda_2 \leq t \leq T \quad (3.23)$$

which yields

$$Q(t) = -\frac{1}{\theta^2} \begin{pmatrix} e^{\theta(\lambda_2 - t)} b_1 \lambda_1 \theta + e^{\theta(\lambda_2 - t)} b_2 \lambda_2 \theta - e^{\theta(t_1 - t)} S \theta^2 - e^{\theta(t_1 - t)} b_1 \lambda_1 \theta \\ + e^{\theta(\lambda_2 - t)} a_1 \theta - e^{\theta(\lambda_2 - t)} a_2 \theta - e^{\theta(t_1 - t)} a_1 \theta - b_2 t \theta - e^{\theta(\lambda_2 - t)} b_2 \\ + a_2 \theta + b_2 \end{pmatrix} \quad (3.24)$$

Using the boundary condition $Q(T) = 0$ in (3.24), we evaluate the maximum level of stock as under:

$$S = \frac{1}{\theta^2 e^{-\theta(T-t_1)}} \begin{pmatrix} b_1 \lambda_1 \theta e^{-\theta(T-\lambda_2)} + b_2 \lambda_2 \theta e^{-\theta(T-\lambda_2)} - b_1 \lambda_1 \theta e^{-\theta(T-t_1)} + a_1 \theta e^{-\theta(T-\lambda_2)} \\ - a_2 \theta e^{-\theta(T-\lambda_2)} - a_1 \theta e^{-\theta(T-t_1)} - b_2 T \theta - b_2 e^{-\theta(T-\lambda_2)} + a_2 \theta + b_2 \end{pmatrix} \quad (3.25)$$

By substituting S in (3.22) and (3.24), we have $Q(t)$ as under,

$$Q(t) = -\frac{1}{\theta^2} \begin{pmatrix} e^{\theta(T-t)} T b_2 \theta - e^{\theta(\lambda_2 - t)} b_1 \lambda_1 \theta - e^{\theta(\lambda_2 - t)} b_2 \lambda_2 \theta - e^{\theta(T-t)} a_2 \theta \\ - e^{\theta(\lambda_2 - t)} a_1 \theta + e^{\theta(\lambda_2 - t)} a_2 \theta + b_1 \lambda_1 \theta - e^{\theta(T-t)} b_2 + e^{\theta(\lambda_2 - t)} b_2 + a_1 \theta \end{pmatrix} \quad (3.26)$$

$$Q(t) = -\frac{1}{\theta^2} \left(e^{\theta(T-t)} T b_2 \theta - e^{\theta(T-t)} a_2 \theta - b_2 t \theta - e^{\theta(T-t)} b_2 + a_2 \theta + b_2 \right) \quad (3.27)$$

Using (3.18), (3.20), (3.26) and (3.27),

The total inventory during $[0, T]$ is ,

$$T I_2 = \int_0^T Q(t) dt = \int_0^{\lambda_1} Q(t) dt + \int_{\lambda_1}^{t_1} Q(t) dt + \int_{t_1}^{\lambda_2} Q(t) dt + \int_{\lambda_2}^T Q(t) dt \quad (3.28)$$

where,

$$\begin{aligned} \int_0^{\lambda_1} Q(t) dt &= \frac{1}{2\theta^3} \begin{pmatrix} b_1\beta\lambda_1^2\theta^2 + 2a_1\beta\lambda_1\theta^2 - b_1\lambda_1^2\theta^2 - 2a_1\lambda_1\theta^2 - 2b_1\beta\lambda_1\theta \\ -2a_1\beta\theta + 2b_1\lambda_1\theta + 2a_1\theta + 2b_1\beta + 2a_1\beta\theta e^{-\theta\lambda_1} - 2b_1 - \\ 2a_1\theta e^{-\theta\lambda_1} - 2b_1\beta e^{-\theta\lambda_1} + 2b_1 e^{-\theta\lambda_1} \end{pmatrix} \\ \int_{\lambda_1}^{t_1} Q(t) dt &= -\frac{1}{\theta^3} \begin{pmatrix} b_1\beta\lambda_1^2\theta^2 - b_1\beta\lambda_1 t_1\theta^2 + a_1\beta\lambda_1\theta^2 - a_1\beta t_1\theta^2 - b_1\lambda_1^2\theta^2 \\ + b_1\lambda_1 t_1\theta^2 - a_1\lambda_1\theta^2 + a_1 t_1\theta^2 + b_1\beta + a_1\beta\theta e^{-\theta\lambda_1} - b_1\beta e^{\theta(\lambda_1-t_1)} \\ - a_1\beta\theta e^{-\theta t_1} - b_1 - a_1\theta e^{-\theta\lambda_1} - b_1\beta e^{-\theta\lambda_1} + b_1 e^{\theta(\lambda_1-t_1)} + a_1\theta e^{-\theta t_1} \\ + b_1\beta e^{-\theta t_1} + b_1 e^{-\theta\lambda_1} - b_1 e^{-\theta t_1} \end{pmatrix} \\ \int_{t_1}^{\lambda_2} Q(t) dt &= -\frac{1}{\theta^3} \begin{pmatrix} b_1\lambda_1\lambda_2\theta^2 - b_1\lambda_1 t_1\theta^2 + a_1\lambda_2\theta^2 - a_1 t_1\theta^2 + b_1\lambda_1\theta + b_2\lambda_2\theta - b_1\lambda_1\theta e^{\theta(\lambda_2-t_1)} \\ - b_2\lambda_2\theta e^{\theta(\lambda_2-t_1)} + T b_2\theta e^{\theta(T-t_1)} - T b_2\theta e^{\theta(T-\lambda_2)} + a_1\theta - a_2\theta - a_1\theta e^{\theta(\lambda_2-t_1)} \\ + a_2\theta e^{\theta(\lambda_2-t_1)} - a_2\theta e^{\theta(T-t_1)} + a_2\theta e^{\theta(T-\lambda_2)} - b_2 + b_2 e^{\theta(\lambda_2-t_1)} \\ - b_2 e^{\theta(T-t_1)} + b_2 e^{\theta(T-\lambda_2)} \end{pmatrix} \\ \int_{\lambda_2}^T Q(t) dt &= -\frac{1}{2\theta^3} \begin{pmatrix} -T^2 b_2\theta^2 + \theta^2 b_2\lambda_2^2 + 2T a_2\theta^2 - 2\theta^2 a_2\lambda_2 + 2T b_2\theta e^{\theta(T-\lambda_2)} \\ - 2b_2\lambda_2\theta - 2a_2\theta e^{\theta(T-\lambda_2)} + 2a_2\theta - 2b_2 e^{\theta(T-\lambda_2)} + 2b_2 \end{pmatrix} \end{aligned}$$

Now, total number of deteriorated units during $[0, T]$ is given by,

$DI_2 = \text{Production in } [0, \lambda_1] + \text{Production in } [\lambda_1, t_1] - \text{Demand in } [0, \lambda_1] - \text{Demand in } [\lambda_1, \lambda_2] - \text{Demand in } [\lambda_2, T]$

$$\begin{aligned} &= \beta \int_0^{\lambda_1} (a_1 + b_1 t) dt + \beta \int_{\lambda_1}^{t_1} (a_1 + b_1 \lambda_1) dt \\ &\quad - \int_0^{\lambda_1} (a_1 + b_1 t) dt - \int_{\lambda_1}^{\lambda_2} (a_1 + b_1 \lambda_1) dt - \int_{\lambda_2}^T (a_2 - b_2 t) dt \\ &= -\frac{1}{2} b_1 \beta \lambda_1^2 + b_1 \beta \lambda_1 t_1 + \beta t_1 a_1 + \frac{1}{2} b_1 \lambda_1^2 - b_1 \lambda_1 \lambda_2 - \lambda_2 a_1 + \frac{1}{2} T^2 b_2 - \frac{1}{2} b_2 \lambda_2^2 - a_2 T + a_2 \lambda_2 \end{aligned} \quad (3.29)$$

Cost of production during $[0, t_1]$ is given by,

$$\begin{aligned} PC_2 &= \int_0^{t_1} \beta \alpha_1 (R(t))^{(1-\gamma)} du \\ &= \int_0^{\lambda_1} \beta \alpha_1 (a_1 + b_1 u)^{(1-\gamma)} du + \int_{\lambda_1}^{t_1} \beta \alpha_1 (a_1 + b_1 \lambda_1)^{(1-\gamma)} du \\ &= \beta \alpha_1 \left(\frac{-a_1^\gamma + (b_1 \lambda_1 + a_1)^\gamma}{b_1 \gamma} + (b_1 \lambda_1 + a_1)^{\gamma-1} (t_1 - \lambda_1) \right) \end{aligned} \quad (3.30)$$

Case 3: $0 \leq t_1 \leq \lambda_1 \leq \lambda_2 \leq T$

For this case, using (3.1),

$$\frac{dQ}{dt} + \theta Q(t) = \begin{cases} (\beta - 1)(a_1 + b_1 t) & ; \quad 0 \leq t \leq t_1 \\ -(a_1 + b_1 t) & ; \quad t_1 \leq t \leq \lambda_1 \\ -(a_1 + b_1 \lambda_1) & ; \quad \lambda_1 \leq t \leq \lambda_2 \\ -(a_2 - b_2 t) & ; \quad \lambda_2 \leq t \leq T \end{cases} \quad (3.31)$$

To solve (3.31), we use the initial condition $Q(0) = 0$,

$$\frac{dQ}{dt} + \theta Q(t) = (\beta - 1)(a_1 + b_1 t); \quad 0 \leq t \leq t_1 \quad (3.32)$$

The solution is

$$Q(t) = \frac{1}{\theta^2} (\beta - 1) (b_1 t \theta + a_1 \theta - b_1 - (a_1 \theta - b_1) e^{-\theta t}) \quad (3.33)$$

At time $t = t_1$ the production stops and the level of stock is at its maximum value S , i.e. $Q(t_1) = S$ and we solve,

$$\frac{dQ}{dt} + \theta Q(t) = -(a_1 + b_1 t); \quad t_1 \leq t \leq \lambda_1 \quad (3.34)$$

which results in

$$Q(t) = \frac{1}{\theta^2} \begin{pmatrix} e^{-\theta(t-t_1)} S \theta^2 + e^{-\theta(t-t_1)} b_1 t_1 \theta + a_1 \theta e^{-\theta(t-t_1)} - b_1 t \theta \\ - b_1 e^{-\theta(t-t_1)} - a_1 \theta - b_1 \end{pmatrix} \quad (3.35)$$

Now, using continuity of the function $Q(t)$ at $t = \lambda_1$ we solve,

$$\frac{dQ}{dt} + \theta Q(t) = -(a_1 + b_1 \lambda_1); \quad \lambda_1 \leq t \leq \lambda_2 \quad (3.36)$$

whose solution is

$$Q(t) = \frac{1}{\theta^2} \begin{pmatrix} e^{-\theta(t-t_1)} S \theta^2 + b_1 t_1 \theta e^{-\theta(t-t_1)} + a_1 \theta e^{-\theta(t-t_1)} - b_1 e^{-\theta(t-t_1)} \\ -b_1 \lambda_1 \theta + b_1 e^{-\theta(t-\lambda_1)} - a_1 \theta \end{pmatrix} \quad (3.37)$$

Again, using the continuity of $Q(t)$ at $t = \lambda_2$, we solve the differential equation,

$$\frac{dQ}{dt} + \theta Q(t) = -(a_2 - b_2 t); \quad \lambda_2 \leq t \leq T \quad (3.38)$$

which gives

$$Q(t) = -\frac{1}{\theta^2} \begin{pmatrix} e^{\theta(\lambda_2-t)} b_1 \lambda_1 \theta + e^{\theta(\lambda_2-t)} b_2 \lambda_2 \theta - e^{\theta(t_1-t)} S \theta^2 - e^{\theta(t_1-t)} b_1 t_1 \theta \\ + e^{\theta(\lambda_2-t)} a_1 \theta - e^{\theta(\lambda_2-t)} a_2 \theta - e^{\theta(t_1-t)} a_1 \theta - b_2 t \theta - e^{\theta(\lambda_2-t)} b_2 \\ + e^{\theta(t_1-t)} b_1 - e^{\theta(\lambda_1-t)} b_1 + a_2 \theta + b_2 \end{pmatrix} \quad (3.39)$$

As similar to other cases, we use the boundary condition $Q(T) = 0$ in (3.39), the maximum level of stock is as below:

$$S = -\frac{1}{\theta^2 e^{-\theta(T-t_1)}} \begin{pmatrix} -b_1 \lambda_1 \theta e^{-\theta(T-\lambda_2)} - b_2 \lambda_2 \theta e^{-\theta(T-\lambda_2)} + b_1 t_1 \theta e^{-\theta(T-t_1)} - a_1 \theta e^{-\theta(T-\lambda_2)} \\ + a_2 \theta e^{-\theta(T-\lambda_2)} + a_1 \theta e^{-\theta(T-t_1)} + b_2 T \theta + b_2 e^{-\theta(T-\lambda_2)} - b_1 e^{-\theta(T-t_1)} \\ + b_1 e^{-\theta(T-\lambda_1)} - a_2 \theta - b_2 \end{pmatrix} \quad (3.40)$$

By substituting S in (3.35), (3.37) and (3.39), we have $Q(t)$ as under,

$$Q(t) = \frac{1}{\theta^2} \begin{pmatrix} b_1 \lambda_1 \theta e^{\theta(\lambda_2-t)} + b_2 \lambda_2 \theta e^{\theta(\lambda_2-t)} + a_1 \theta e^{\theta(\lambda_2-t)} - a_2 \theta e^{\theta(\lambda_2-t)} \\ -T b_2 \theta e^{\theta(T-t)} - b_2 e^{\theta(\lambda_2-t)} - b_1 e^{\theta(\lambda_1-t)} + a_2 \theta e^{\theta(T-t)} + b_2 e^{\theta(T-t)} \\ -b_1 t \theta - a_1 \theta + b_1 \end{pmatrix} \quad (3.41)$$

$$Q(t) = \frac{1}{\theta^2} \begin{pmatrix} b_1 \lambda_1 \theta e^{\theta(\lambda_2-t)} + b_2 \lambda_2 \theta e^{\theta(\lambda_2-t)} + a_1 \theta e^{\theta(\lambda_2-t)} - a_2 \theta e^{\theta(\lambda_2-t)} \\ -T b_2 \theta e^{\theta(T-t)} - b_2 e^{\theta(\lambda_2-t)} + a_2 \theta e^{\theta(T-t)} + b_2 e^{\theta(T-t)} - b_1 \lambda_1 \theta - a_1 \theta \end{pmatrix} \quad (3.42)$$

$$Q(t) = -\frac{1}{\theta^2} \begin{pmatrix} T b_2 \theta e^{\theta(T-t)} - a_2 \theta e^{\theta(T-t)} - b_2 t \theta - b_2 e^{\theta(T-t)} + a_2 \theta + b_2 \end{pmatrix} \quad (3.43)$$

Using (3.33), (3.41), (3.42) and (3.43),

Total inventory during $[0, T]$ is ,

$$T I_3 = \int_0^T Q(t) dt = \int_0^{t_1} Q(t) dt + \int_{t_1}^{\lambda_1} Q(t) dt + \int_{\lambda_1}^{\lambda_2} Q(t) dt + \int_{\lambda_2}^T Q(t) dt \quad (3.44)$$

where,

$$\begin{aligned} \int_0^{t_1} Q(t) dt &= \frac{1}{2\theta^3} \begin{pmatrix} b_1 \beta t_1^2 \theta^2 + 2a_1 \beta t_1 \theta^2 - b_1 t_1^2 \theta^2 - 2a_1 t_1 \theta^2 - 2b_1 \beta t_1 \theta \\ -2a_1 \beta \theta + 2b_1 t_1 \theta + 2a_1 \theta + 2b_1 \beta - 2b_1 + (2a_1 \beta \theta - 2a_1 \theta - 2b_1 \beta + 2b_1) e^{-\theta t_1} \end{pmatrix} \\ \int_{t_1}^{\lambda_1} Q(t) dt &= -\frac{1}{2\theta^3} \begin{pmatrix} b_1 \lambda_1^2 \theta^2 - b_1 t_1^2 \theta^2 + 2a_1 \lambda_1 \theta^2 - 2a_1 t_1 \theta^2 - 2b_1 \lambda_1 \theta e^{\theta(\lambda_2-t_1)} \\ -2b_2 \lambda_2 \theta e^{\theta(\lambda_2-t_1)} + 2b_1 \lambda_1 \theta e^{\theta(\lambda_2-\lambda_1)} + 2b_2 \lambda_2 \theta e^{\theta(\lambda_2-\lambda_1)} \\ + 2T b_2 \theta e^{\theta(T-t_1)} - 2T b_2 \theta e^{\theta(T-\lambda_1)} - 2b_1 \lambda_1 \theta + 2b_1 t_1 \theta \\ -2a_1 \theta e^{\theta(\lambda_2-t_1)} + 2a_2 \theta e^{\theta(\lambda_2-t_1)} + 2a_1 \theta e^{\theta(\lambda_2-\lambda_1)} - 2a_2 \theta e^{\theta(\lambda_2-\lambda_1)} \\ -2a_2 \theta e^{\theta(T-t_1)} + 2a_2 \theta e^{\theta(T-\lambda_1)} + 2b_2 e^{\theta(\lambda_2-t_1)} - 2b_2 e^{\theta(\lambda_2-\lambda_1)} - 2b_2 e^{\theta(T-t_1)} \\ + 2b_2 e^{\theta(T-\lambda_1)} + 2b_1 e^{\theta(\lambda_1-t_1)} - 2b_1 \end{pmatrix} \\ \int_{\lambda_1}^{\lambda_2} Q(t) dt &= \frac{1}{\theta^3} \begin{pmatrix} b_1 \lambda_1^2 \theta^2 - b_1 \lambda_1 \lambda_2 \theta^2 + a_1 \lambda_1 \theta^2 - a_1 \lambda_2 \theta^2 - b_1 \lambda_1 \theta - b_2 \lambda_2 \theta \\ + T b_2 \theta e^{\theta(T-\lambda_2)} + b_1 \lambda_1 \theta e^{\theta(\lambda_2-\lambda_1)} + b_2 \lambda_2 \theta e^{\theta(\lambda_2-\lambda_1)} - T b_2 \theta e^{\theta(T-\lambda_1)} \\ - a_1 \theta + a_2 \theta - a_2 \theta e^{\theta(T-\lambda_2)} + a_1 \theta e^{\theta(\lambda_2-\lambda_1)} - a_2 \theta e^{\theta(\lambda_2-\lambda_1)} + a_2 \theta e^{\theta(T-\lambda_1)} \\ + b_2 - b_2 e^{\theta(T-\lambda_2)} - b_2 e^{\theta(\lambda_2-\lambda_1)} + b_2 e^{\theta(T-\lambda_1)} \end{pmatrix} \end{aligned}$$

$$\int_{\lambda_2}^T Q(t) dt = \frac{1}{2\theta^3} \begin{pmatrix} T^2 b_2 \theta^2 - \lambda_2^2 b_2 \theta^2 - 2T a_2 \theta^2 + 2a_2 \theta^2 \lambda_2 + 2b_2 \lambda_2 \theta \\ -2T b_2 \theta e^{\theta(T-\lambda_2)} - 2a_2 \theta + 2a_2 \theta e^{\theta(T-\lambda_2)} - 2b_2 + 2b_2 e^{\theta(T-\lambda_2)} \end{pmatrix}$$

Now, the total number of deteriorated units during $[0, T]$ is given by,

$DI_3 = \text{Production in } [0, t_1] - \text{Demand in } [0, \lambda_1] - \text{Demand in } [\lambda_1, \lambda_2] - \text{Demand in } [\lambda_2, T]$

$$\begin{aligned} &= \beta \int_0^{t_1} (a_1 + b_1 t) dt - \int_0^{\lambda_1} (a_1 + b_1 t) dt - \int_{\lambda_1}^{\lambda_2} (a_1 + b_1 \lambda_1) dt - \int_{\lambda_2}^T (a_2 - b_2 t) dt \\ &= \frac{1}{2} b_1 \beta t_1^2 + a_1 \beta t_1 + \frac{1}{2} b_1 \lambda_1^2 - b_1 \lambda_1 \lambda_2 - a_1 \lambda_2 + \frac{1}{2} T^2 b_2 - \frac{1}{2} b_2 \lambda_2^2 - a_2 T + a_2 \lambda_2 \end{aligned} \quad (3.45)$$

Cost of production during $[0, t_1]$ is given by,

$$\begin{aligned} PC_3 &= \int_0^{t_1} \beta \alpha_1 (R(t))^{(1-\gamma)} du = \int_0^{t_1} \beta \alpha_1 (a_1 + b_1 u)^{(1-\gamma)} du \\ &= \beta \alpha_1 \left(\frac{-a_1^\gamma + (b_1 t_1 + a_1)^\gamma}{b_1 \gamma} \right) \end{aligned} \quad (3.46)$$

The Total cost of an inventory system is defined as the sum of the Inventory holding cost, the Deterioration cost and the Purchase cost. For all the three cases discussed above, we denote and define this as under:

$$C(t_1, T) = \begin{cases} C_1(t_1, T) = \frac{1}{T} [C_h T I_1 + C_d D I_1 + P C_1] & ; \quad 0 \leq \lambda_1 \leq \lambda_2 \leq t_1 \leq T \\ C_2(t_1, T) = \frac{1}{T} [C_h T I_2 + C_d D I_2 + P C_2] & ; \quad 0 \leq \lambda_1 \leq t_1 \leq \lambda_2 \leq T \\ C_3(t_1, T) = \frac{1}{T} [C_h T I_3 + C_d D I_3 + P C_3] & ; \quad 0 \leq t_1 \leq \lambda_1 \leq \lambda_2 \leq T \end{cases} \quad (3.47)$$

To find the optimal values of t_1 and T , which minimizes total cost of an inventory system $C(t_1, T)$, we use fundamental calculus. Solve $\frac{\partial C_i}{\partial t_1} = 0$ and $\frac{\partial C_i}{\partial T} = 0$ simultaneously to find t_1 and T , provided that they satisfy the sufficient conditions $\frac{\partial^2 C_i}{\partial t_1^2} > 0$, $\frac{\partial^2 C_i}{\partial T^2} > 0$ and $\frac{\partial^2 C_i}{\partial t_1^2} \frac{\partial^2 C_i}{\partial T^2} - \left(\frac{\partial^2 C_i}{\partial t_1 \partial T} \right)^2 > 0$, where $i = 1, 2, 3$.

Computational Algorithm

Step 1: Assign values to the parameters.

Step 2: Compute t_1 and T using $\frac{\partial C_i}{\partial t_1} = 0$, $\frac{\partial C_i}{\partial T} = 0$ for $i = 1, 2, 3$.

Step 3: If $0 \leq \lambda_1 \leq \lambda_2 \leq t_1 \leq T$ then $C_1(t_1, T)$ is optimal, compute $C_1(t_1, T)$ and S using (3.11), else go to Step 4.

Step 4: If $0 \leq \lambda_1 \leq t_1 \leq \lambda_2 \leq T$ then $C_2(t_1, T)$ is optimal, compute $C_2(t_1, T)$ and S using (3.25), else $C_3(t_1, T)$ is optimal, compute $C_3(t_1, T)$ and S using (3.40).

4 Concluding remarks

To implement the computational algorithm, one needs to evaluate optimal values of t_1 and T by solving the equations $\frac{\partial C_i}{\partial t_1} = 0$, $\frac{\partial C_i}{\partial T} = 0$ case wise for $i = 1, 2, 3$. As equations $\frac{\partial C_i}{\partial t_1} = 0$ and $\frac{\partial C_i}{\partial T} = 0$ are highly nonlinear functions of t_1 and T , one may use Newton Raphson method for suitable values of $a_1, b_1, a_2, b_2, \lambda_1, \lambda_2, \theta, \gamma$ and α_1 , to find optimal values of t_1^* and T^* . So, the corresponding minimum value of the average cost of an inventory system $C(t_1^*, T^*)$ is minimum. Convexity of cost function is difficult to discuss analytically. This says $C(t_1^*, T^*)$ may not be global minimum but may be local minimum. One may extend this model, using advance optimization techniques like, PSO, GA etc. to find the minimum cost of an inventory system.

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